1. Ball Drop
- Add Sensor Plate and Claw with Hinge Arms pinned back.
- Align with "U".
- Ball in Claw.
- Program 1

2. Serve Food
- Remove Claw
- Release Hinge Arm #1 Pull Blue Pin on Claw.
- Bring Hinge Arm #2 Forward
- Attach Hinge Arms to Top Claw Gear
- Add Counter Weight
- Align with "U" – brick to far edge, 2 spacers
- Program 2

3. Bus Route
- Remove Claw (Black and White)
- Remove Hinge Arm #2
- Remove Sight
- Remove Counter Weight
- Add Whacker
- Add Chair Pusher Axle
- Position Light Sensor
- Align for Calibration – read white count
- Program 3

4. Push CD
- Add CD Pusher
- [Remove Sensor Plate? – unplug A but reposition Light Sensor 1 so Touch sensor forward.]

5. Feed Pets
- Position Touch Sensor On Front
- Add Food Server
- Program 5