

ROBOT DESIGN

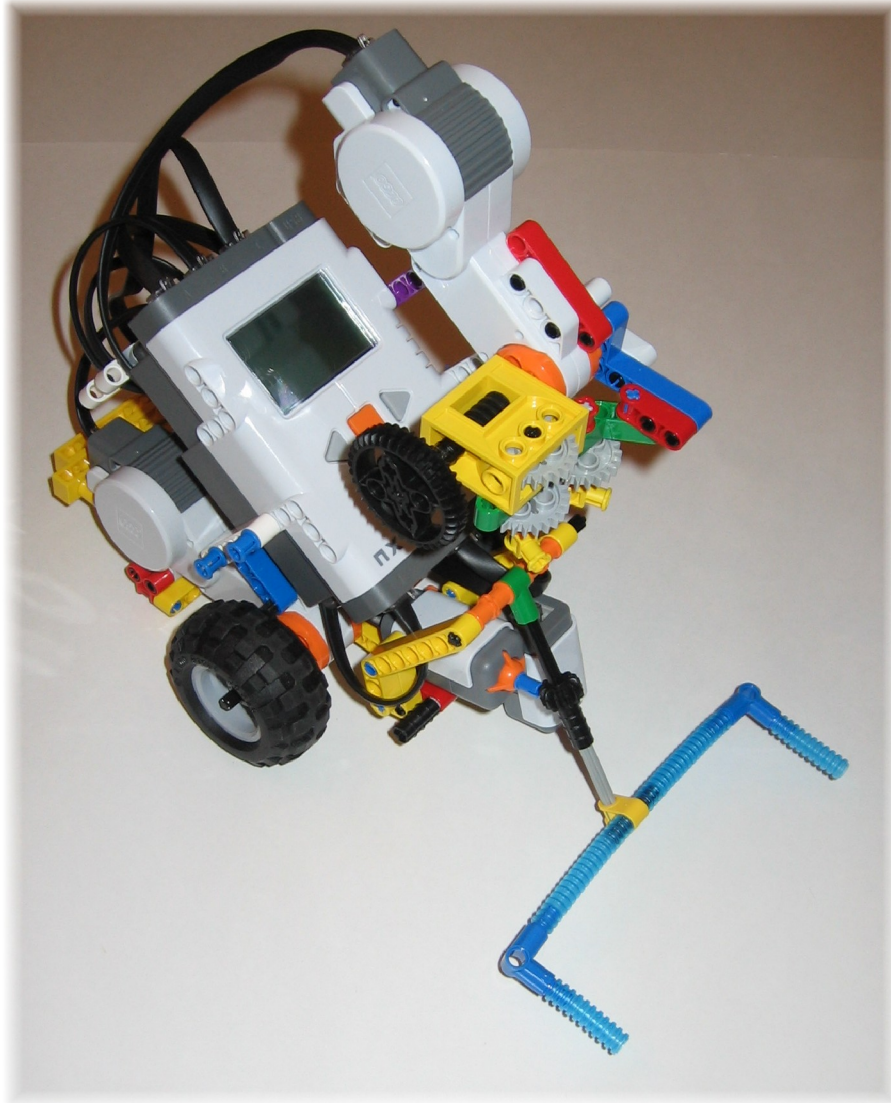


SCORPACUDAS

TEAM # 550

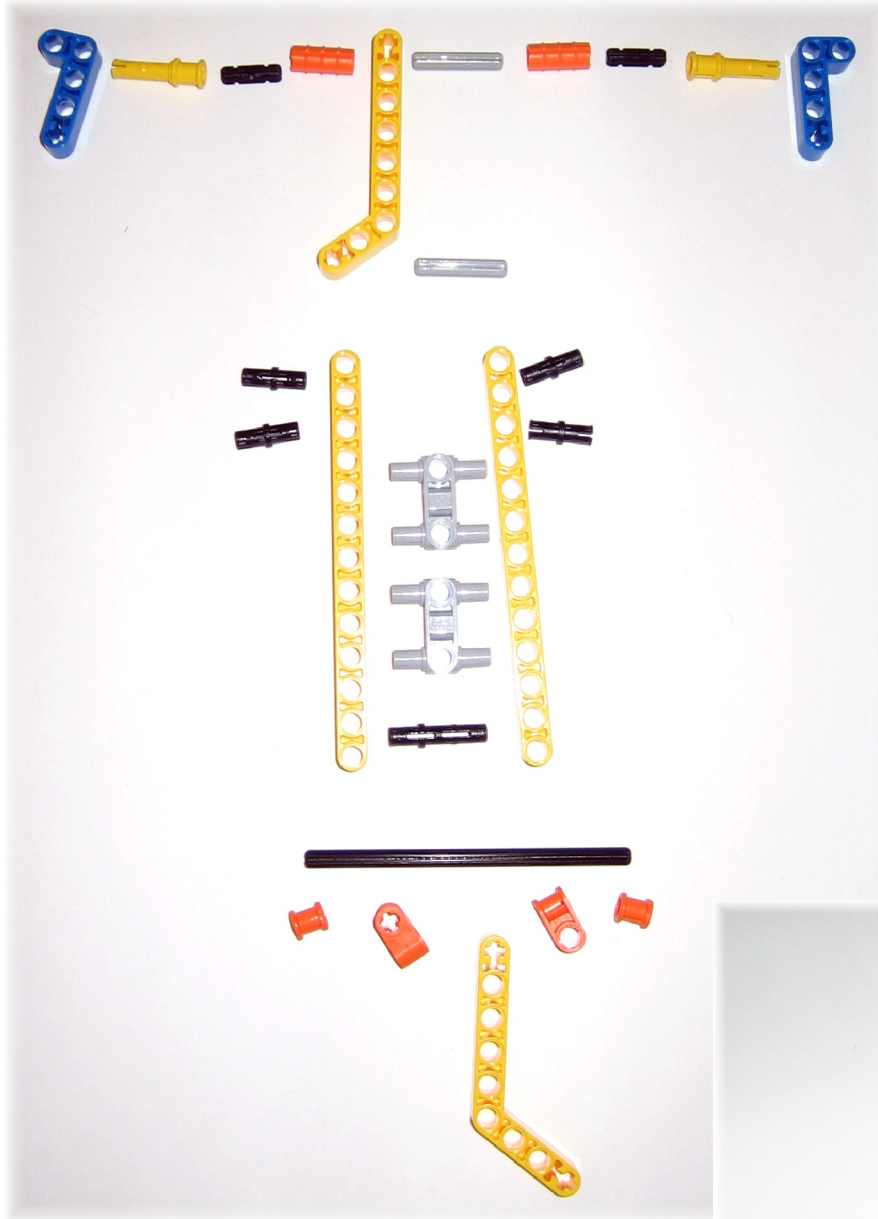


ROBOT DESIGN

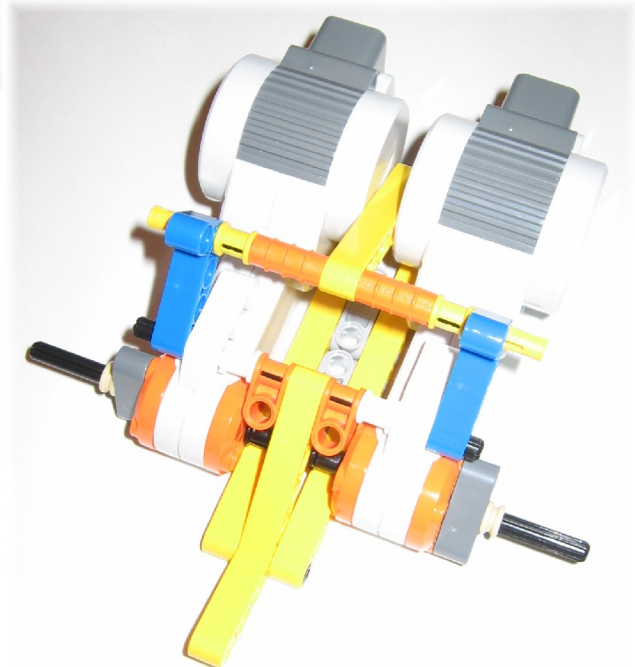
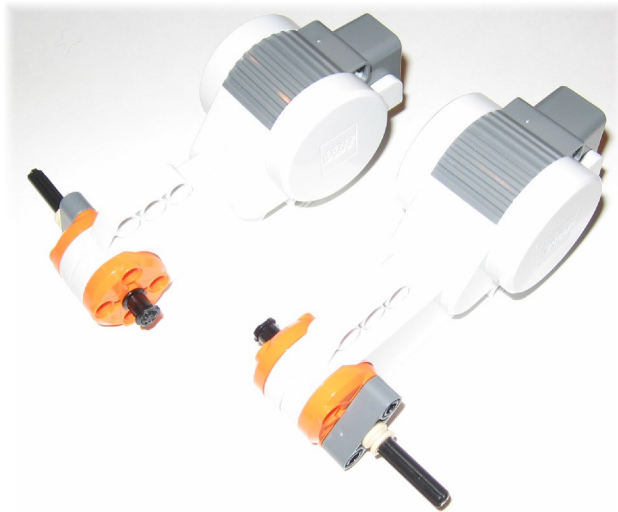
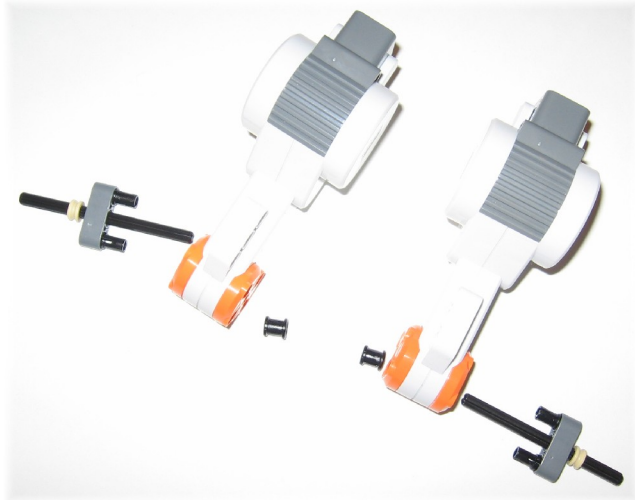
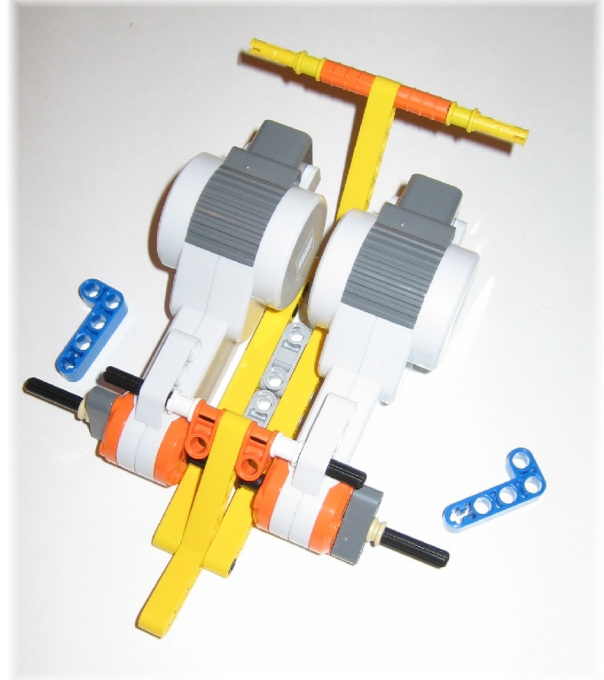
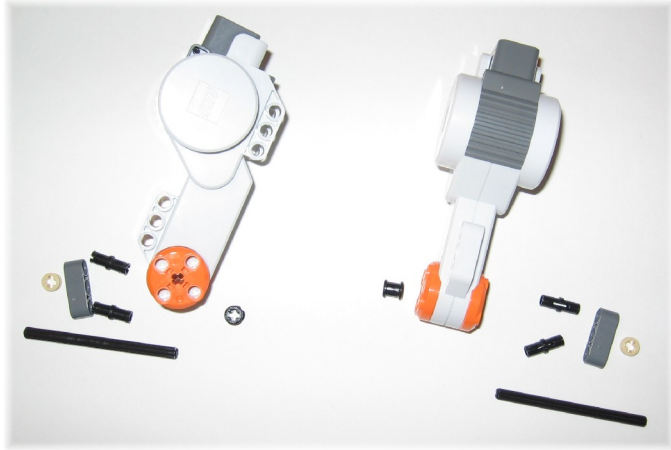


SCORPACUDAS
TEAM #550

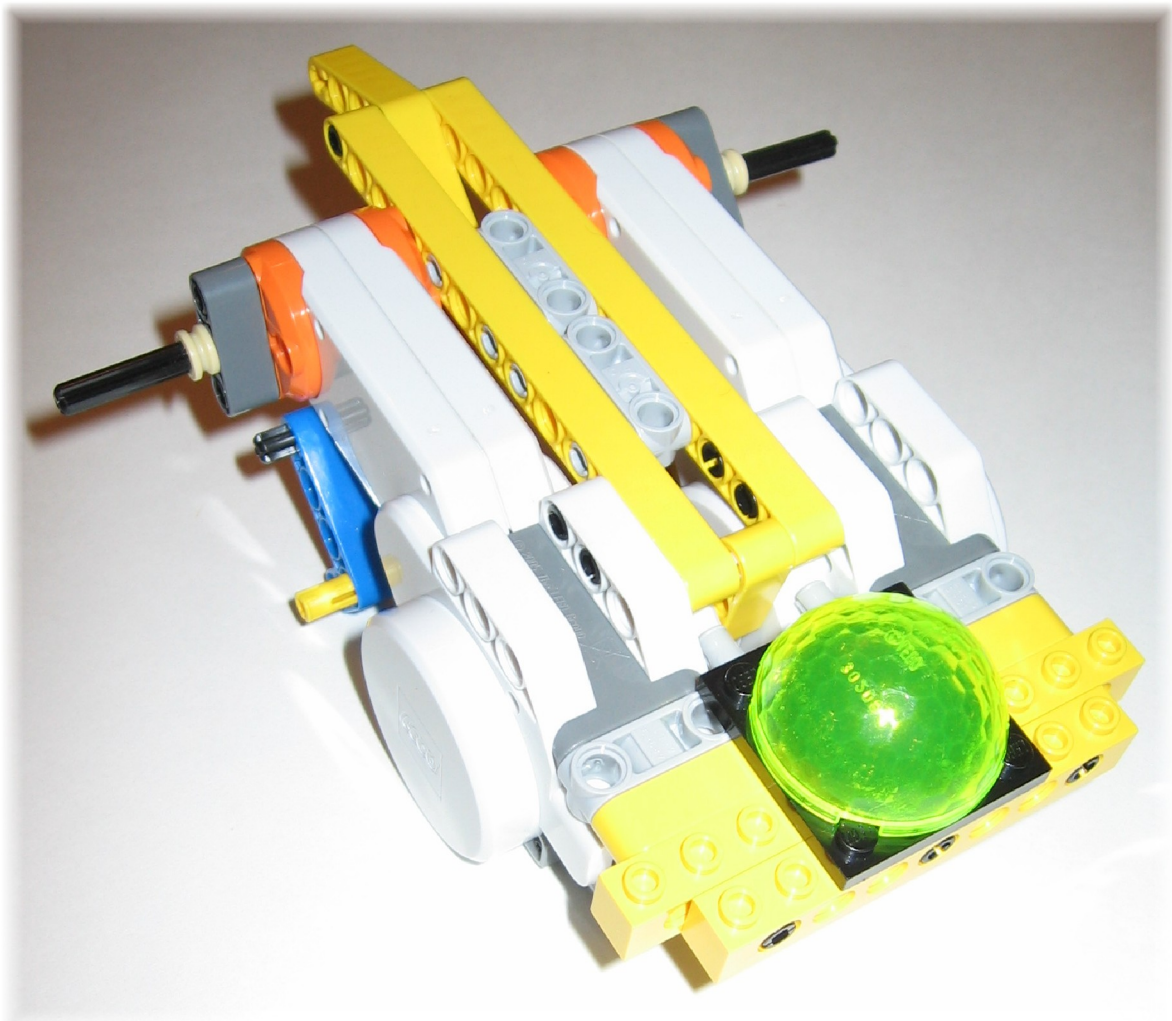
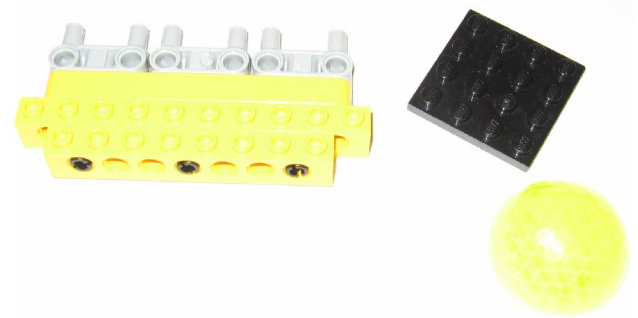
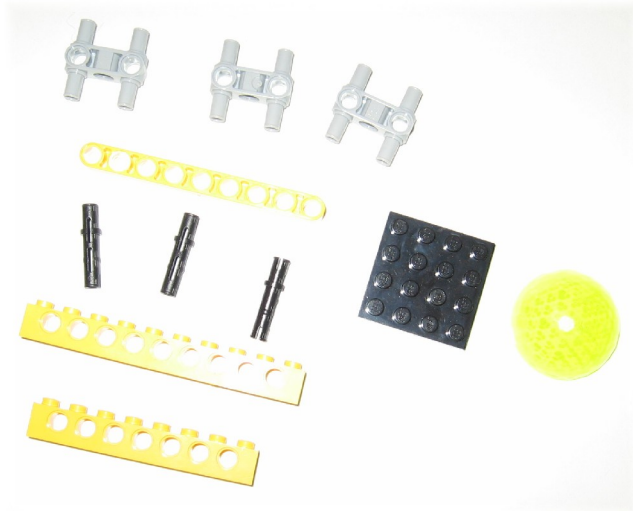
DRIVE



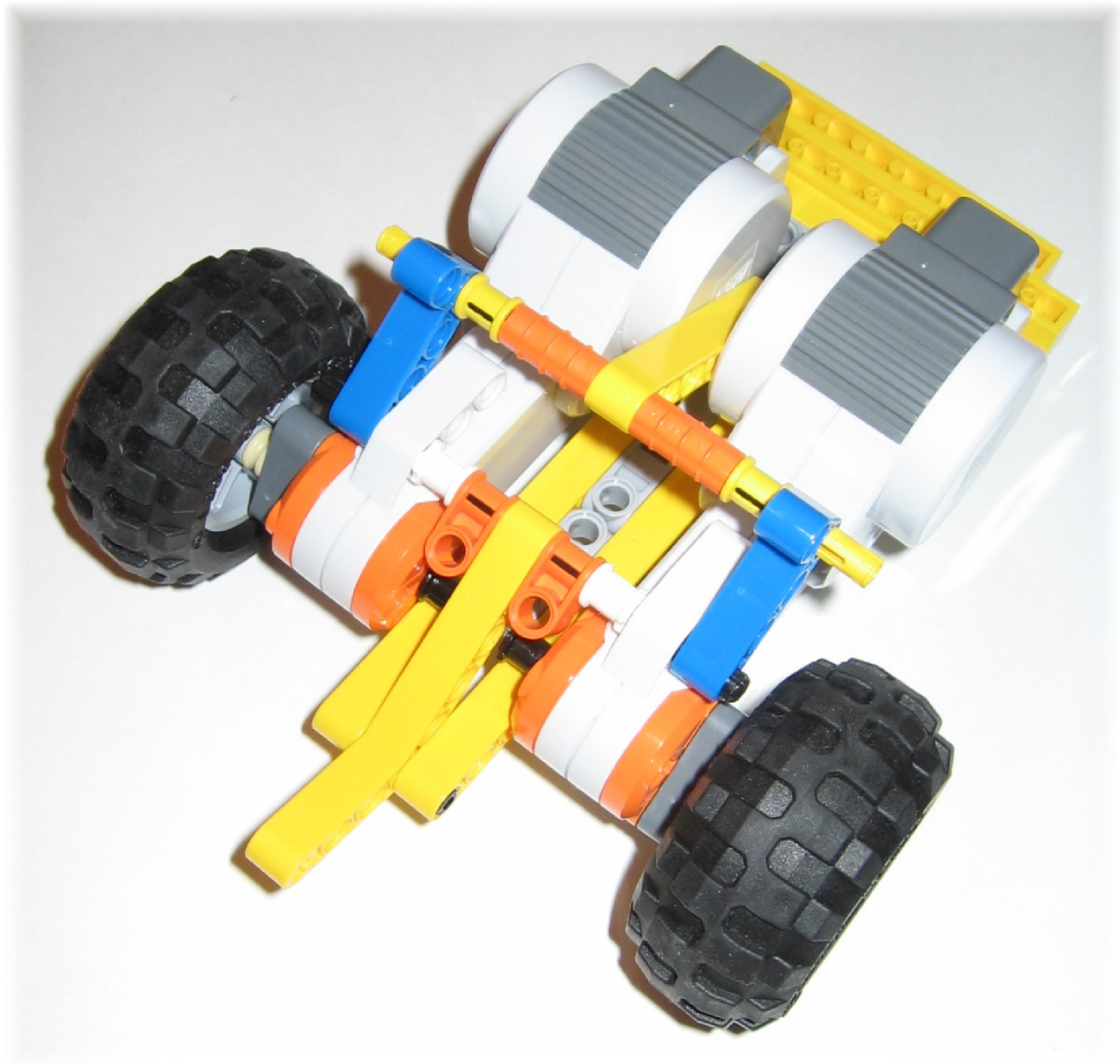
DRIVE



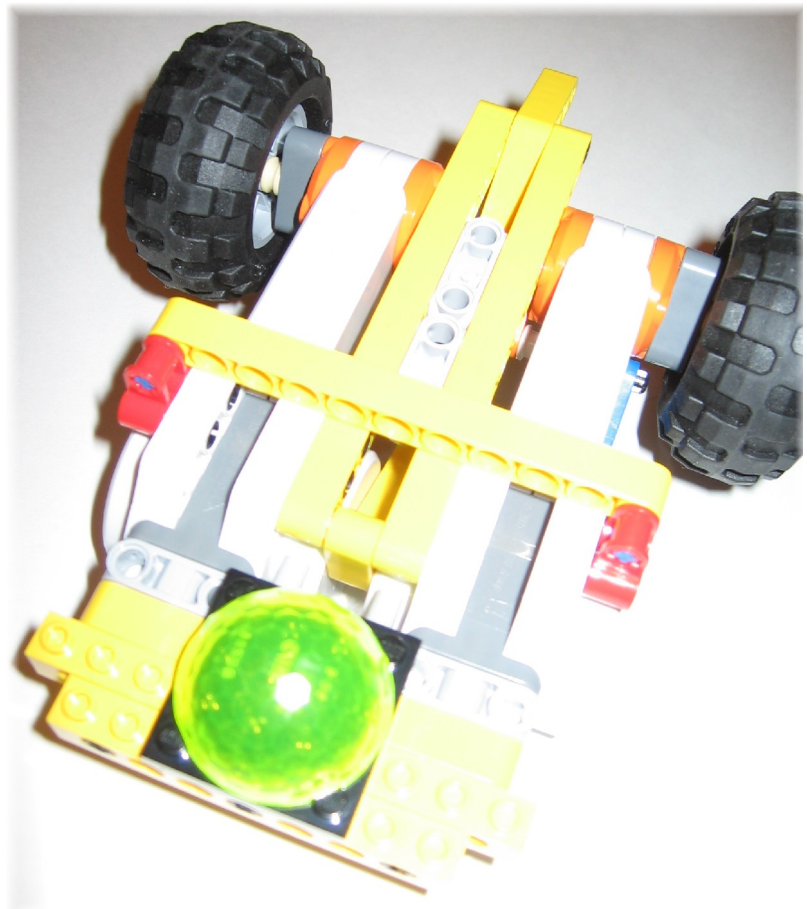
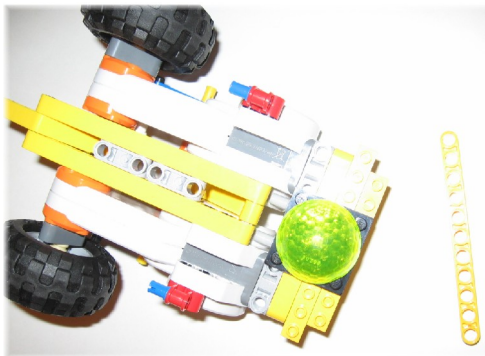
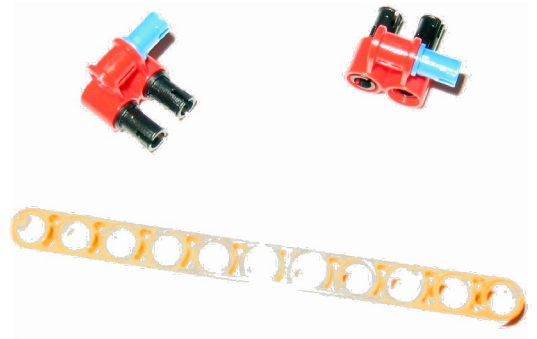
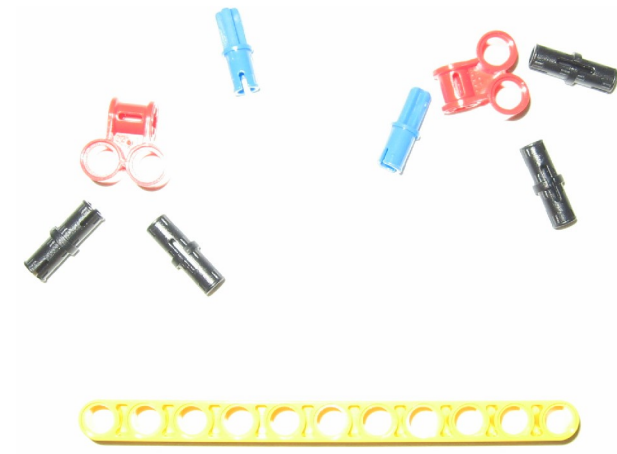
SKID (ONE DESIGN)



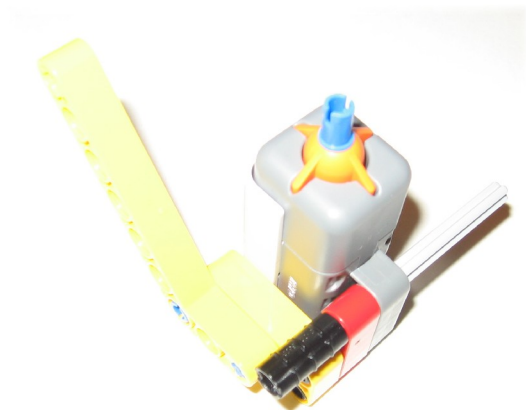
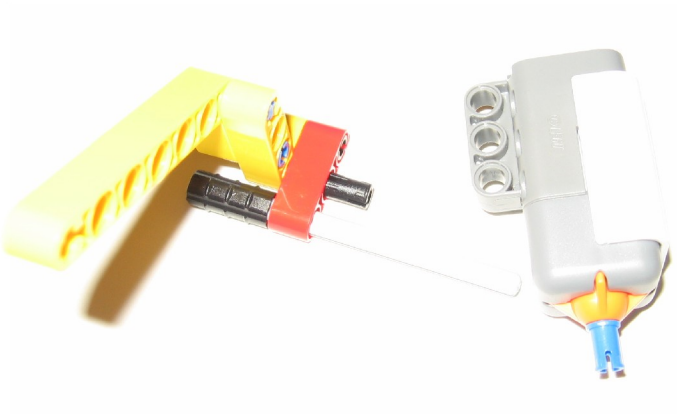
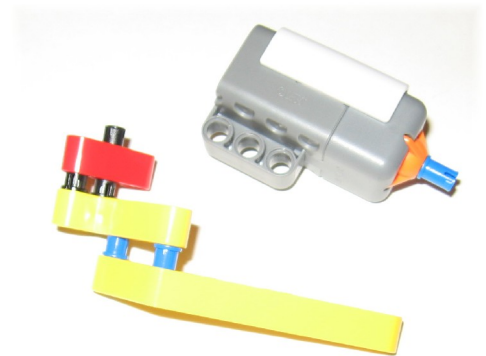
WHEELS



DRIVE BRACING



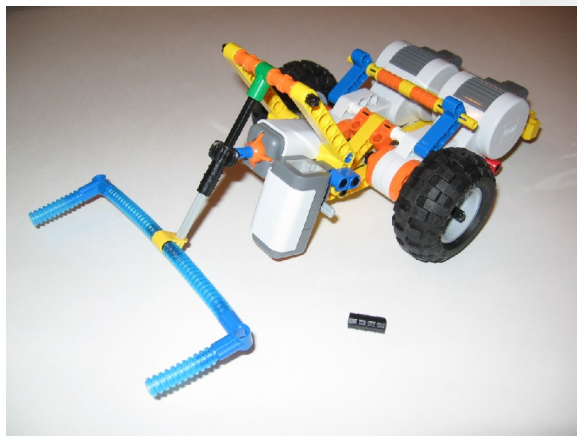
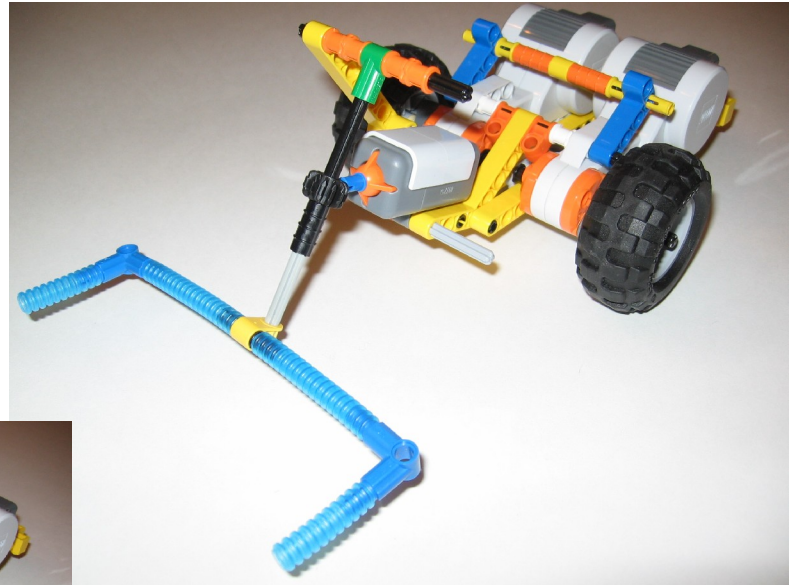
TOUCH SENSOR



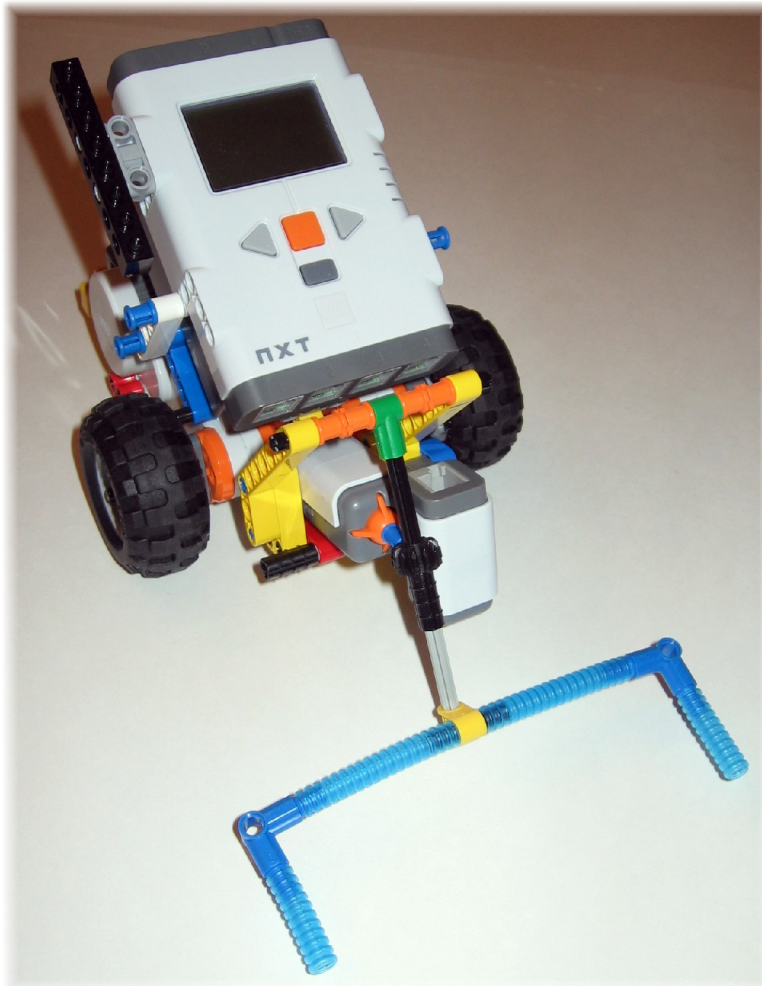
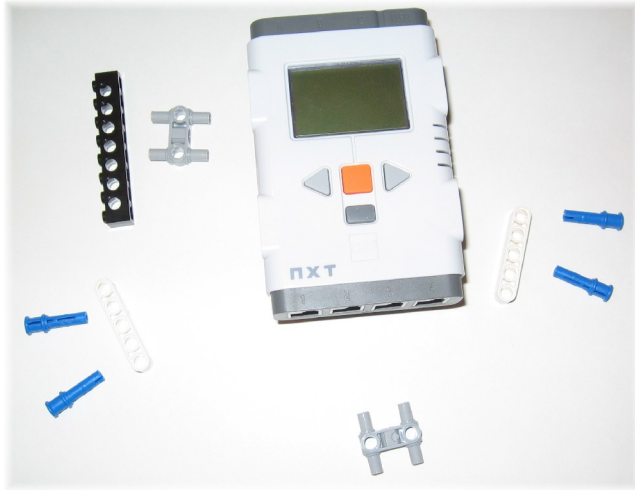
BUMPER



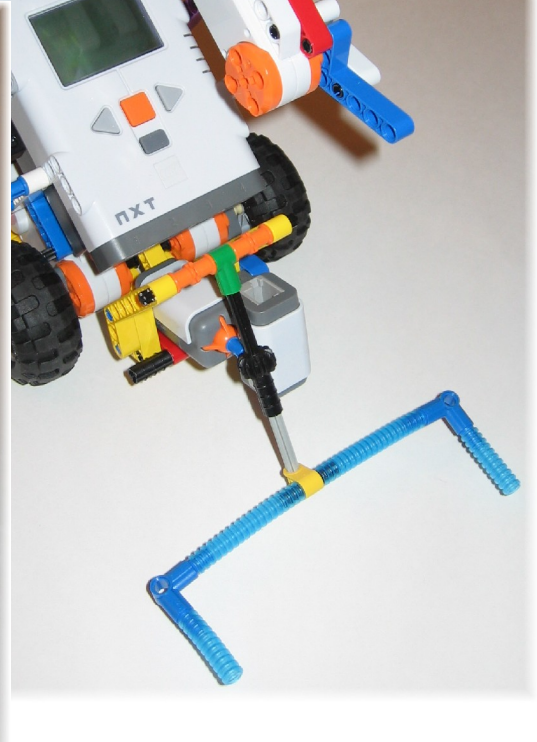
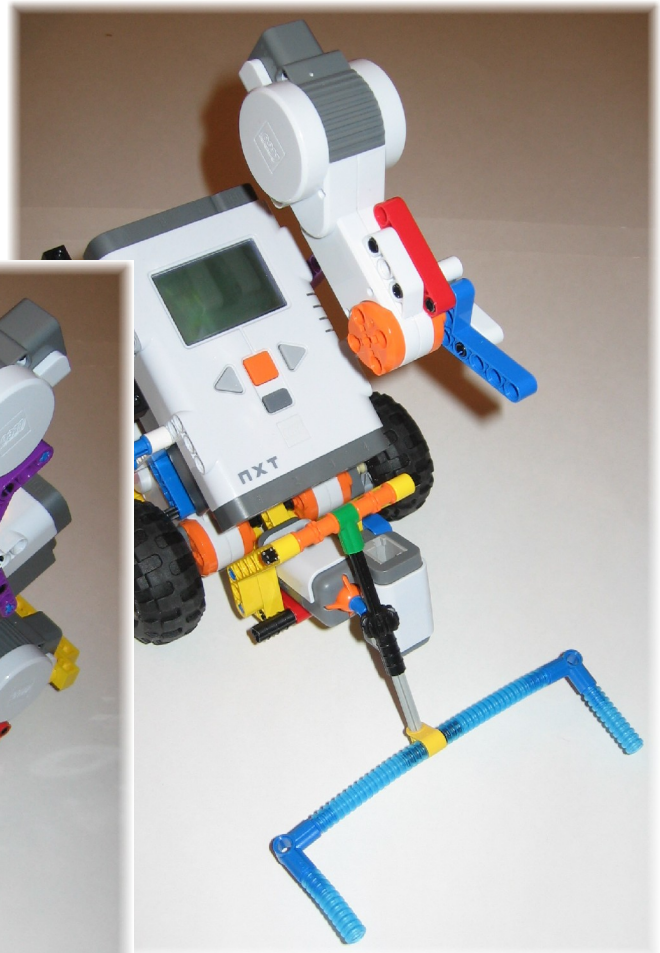
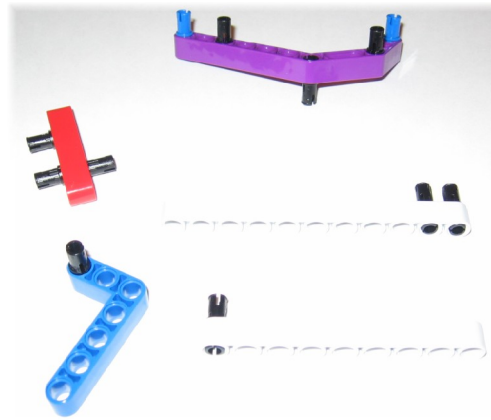
SENSOR INTEGRATION



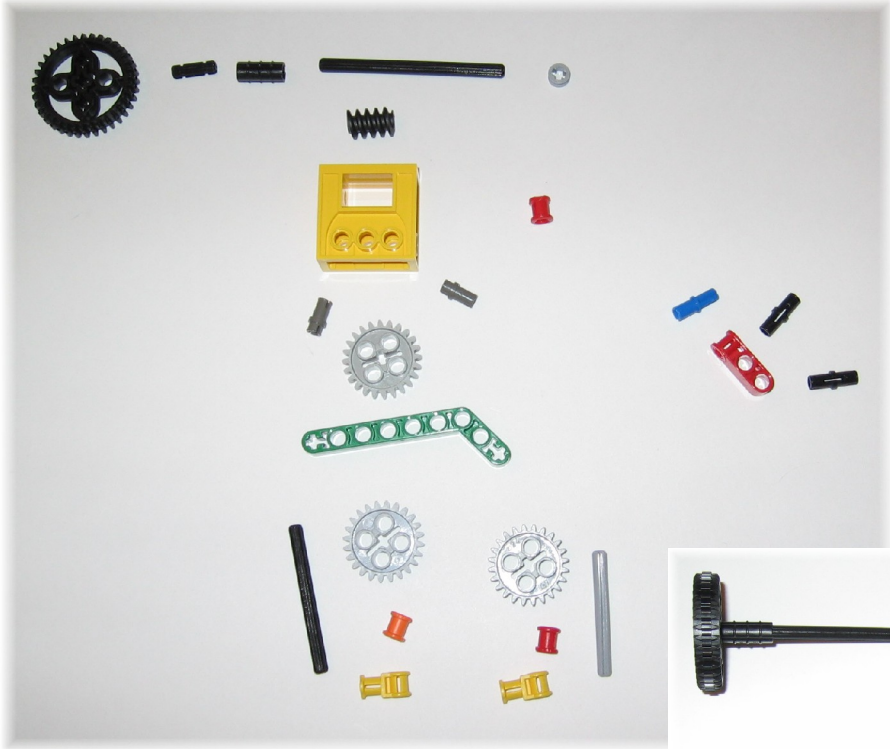
NXT



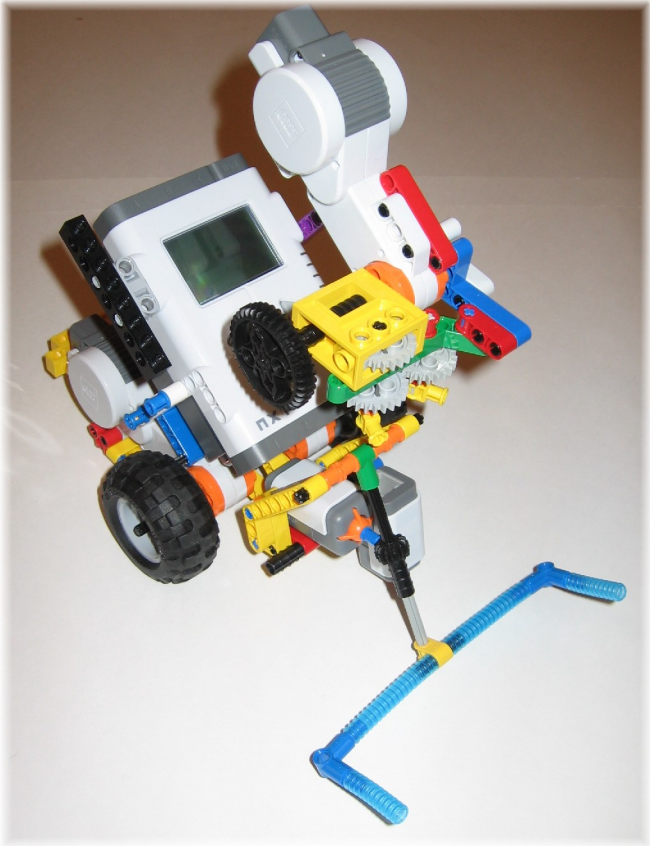
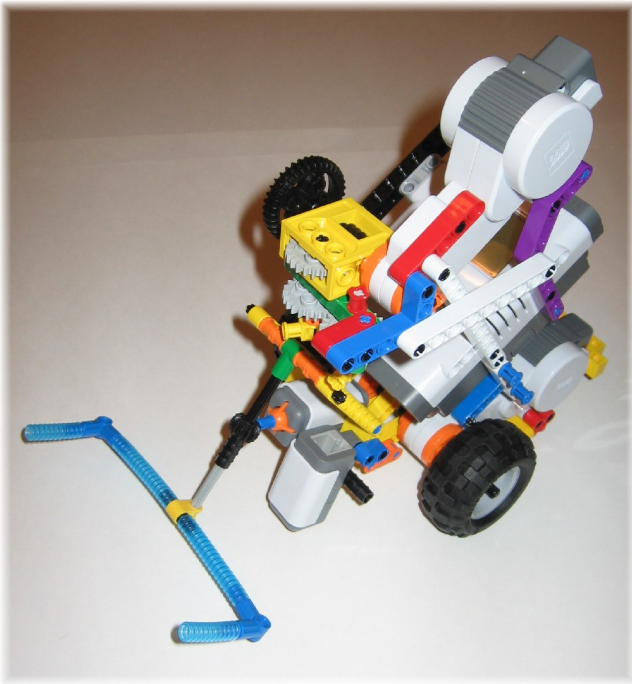
MANIPULATOR MOTOR



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FINAL ROBOT

